





The ISE HYSUB Remotely Operated Vehicle (ROV) is a **fully customizable work class ROV** which is optimized for your operational profile. Select your payloads, depth, power, and frame size to receive your customized HYSUB in as little as 6 months! Every HYSUB is **designed to last for decades** in harsh conditions and is easy to **modify and upgrade** when new technology becomes available.



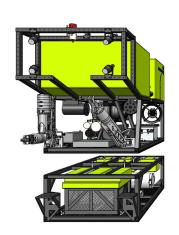
# **APPLICATIONS**

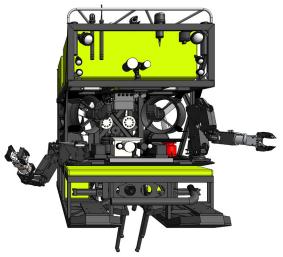
- Inspection and Intervention
- Construction and Drill Support
- Recovery and Salvage
- Cable and Pipe Burial and Inspection
- Ocean Science and Sampling
- Hydrographic and Site Survey



## **INDUSTRIES**

- Environmental Monitoring
- Commercial Offshore
- Oil & Gas
- Mining
- Scientific Research





# **PAYLOADS AND TOOLING**

The HYSUB can be equipped with any equipment, payloads, and tools designed for use on an ROV. These include:

- Jetting Skid for trenching and cable burial
- Suction Samplers, Sample Baskets, and Collection Systems
- Core Sampler, Clathrate Sampler
- Ultra HD Camera and Light Systems
- Hydrographic Survey Skid
- Cable and Pipe Tracking, CP, and Survey Skid
- 7 Function Manipulators and 5 Function Grabbers
- Cable, rope, and chain cutters

## **FEATURES & CAPABILITIES**

These are the features that are built into the HYSUB to ensure our customers achieve great results:



**CUSTOMIZATION:** set up your ROV to optimize your operations

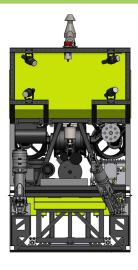


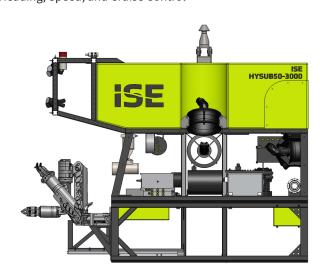
RUGGED AND RELIABLE: HYSUB has a proven track record of being able to take a beating in real world conditions



Change your tools, cameras, lights, skids and components to suit your operation

- **Upgradability:** Spare I/O channels, mounting locations, and payload capacity for adding and removing equipment
- **Auto-functions:** Station Keeping, Depth, Altitude, Heading, Speed, and Cruise Control
- Line Follow and Mission Planning: Use ISE AUV mission planning software to allow your HYSUB to perform tasks autonomously
- USBL/LBL positioning
- LARS, TMS and Winch Options: Top-hat or Garage TMS. A-Frame, Cursor, or Gantry LARS. Up to 7000m Winch





# **SPECIFICATION**

### **ROV PERFORMANCE**

- Depth Ratings: 100-6000 m
- Power: 25—250 hp (19 kW—186 kW)
- Bollard Pull: 370 kg (50 hp), 500 kg (100 hp), 1100 kg (150 hp)
- Surface speed: up to 1.9 m/s (3.7 kts)
- Hydraulic Thrusters: 4 x 12"—19.5" Horizontal (vector or XYZ)

2 or 3 x 12"-16" Vertical

- Through Frame Lift: 500 kg-1000 kg\*
- Payload: 100-200 kg\*

#### **WEIGHT AND DIMENSIONS**

Length: 2.5—3.45 m
Width: 1.0—2.0 m
Height: 1.0—2.3 m\*\*
Weight: 700—5700 kg\*\*\*

### **MANIPULATORS AND GRABBERS\***

- $\bullet$  Standard: ISE Magnum 7F and 5F\*
- Optional: TITAN 4, ORION, Rigmaster,

Predator\*

• Multiple mounting locations

## STANDARD EQUIPMENT

- Scanning Sonar: Imagenex 881a\*
- TOGS NAV\*: Depths, heading, speed, altitude
- Cameras: 1 x 1080p HD Colour Zoom
  - 1 x Low Light
  - 4 x POV SD Colour
- Lights: 6 x 6000 Lumen
  - 2 x 18000 Lumen (Optional)\*
- Pan and Tilt: Electric or Hydraulic
- Beacons: MetOcean Novatech RF & Strobe\*
- Wireless Bellypack

### **SOFTWARE AND COMPUTERS**

• ISE Automated Control Engine (ACE) modular, upgradable, field proven, multiplatform software

#### SPARE CHANNELS, UPGRADES AND ADD-ONS

- Power: 24 VDC @150 Wm, 120 VAC @ 2.3 kVa, 240 VAC @ 1.2 kVa
- Lights: 2 x 250 W Ports @ Light Junction Can
- 5 x RS232, 3 x RS485/422, 2 x Ethernet, 2 x Spare Fibres
- Video: 2 x SD Channels
- Navigation: INS, DVL, USBL & LBL Beacons
- Payloads and Sensors: Can accept CTD, Sonars (MBES, SSS, SBP, SAS), Environmental Sensors, and Scientific Payloads

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<sup>\*</sup>Others available upon request

<sup>\*\*</sup> Not including skid

<sup>\*\*\*</sup> Based on selected options and skid